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ROBOTS AND EDUCATION





World Skills Leipzig 2013

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- Introduction Mitsubishi Electric Europe
- Robot Portfolio 2013
- In what we differ to others?
- Industrial robot applications
- School and university projects
- Summary and discussion





Our corporate statement, "Changes for the Better" signifies the goal and stance of the Mitsubishi Electric Group to continually innovate for the better.

Changes for the Better





SAMSUNG

 Highly innovative efforts with 6 independent R&D-Centers for industrial automation





Mitsubishi Electric History



1870	Tsukumo Trading Company, which was the origin of Mitsubishi, was established.	P
1886	Mitsubishi Corporation was established.	The founder, Yataro Iwasaki
1917	Mitsubishi Headquarters became a holding company.	
1921►	Mitsubishi Electric Corporation was established.	Origin of the Three- Diamond Mark
1945	Mitsubishi Headquarters was dissolved.	
1946	Each Mitsubishi company started as a new independent entity.	



Mitsubishi Worldwide



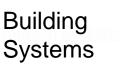




Mitsubishi Electric Worldwide









Factory Automation Systems



Information/ Communication Systems



Air Conditioning Systems



Semiconductors/ Devices



Visual Information Systems



Space Systems



Transportation Systems



Public Systems



Energy Systems



Automotive Equipment



Home Products



Product Portfolio







Robot portfolio 2013



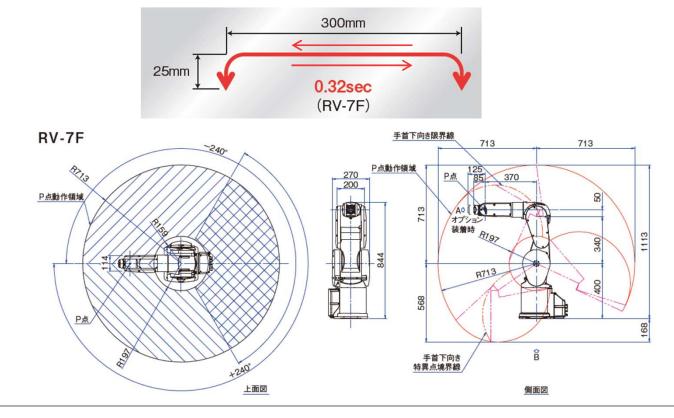




Highlights of the robots

- 0.29 seconds for 12"-Cycle for more productivity
- IP67 as standard for full integration (water washable)
- Wide operating range for maximum flexibility







Biggest working range in its class







Biggest working range in its class



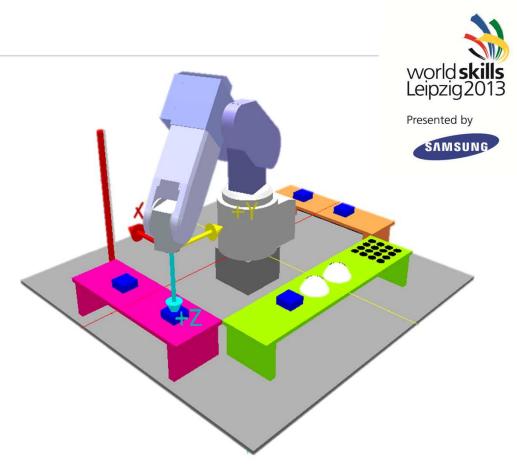






Special features and functions IN WHAT WE DIFFER TO OTHERS?



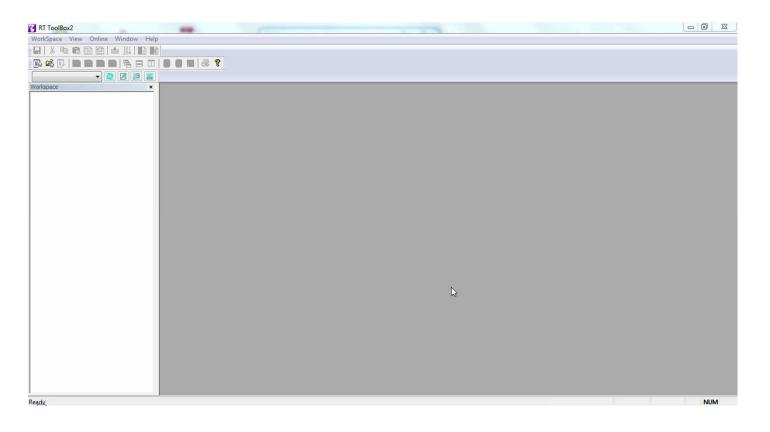


RT ToolBox2, R3-Protokoll, Real-Time Control ROBOT SOFTWARE



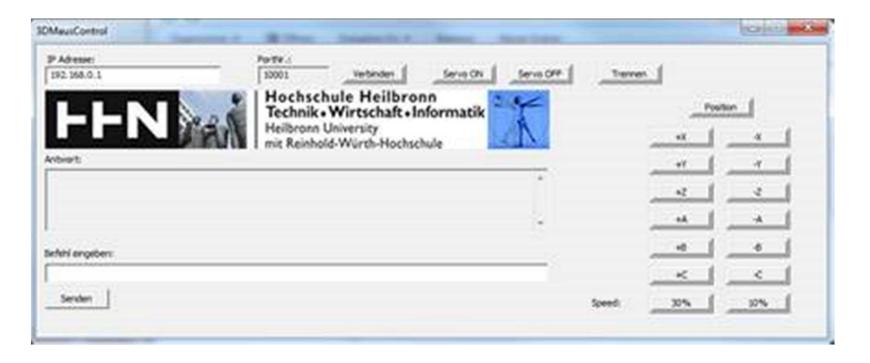


- Easy robot programming
- Accessable for everybody in educational fields





- Control of the robot directly over a PC
- Direct exchange of Programs, Data, I/Os etc.
- No need of robot programming language







- Manipulating the robot over a real-time system
- Programming via C++
- Absolute freedom of scientific programming

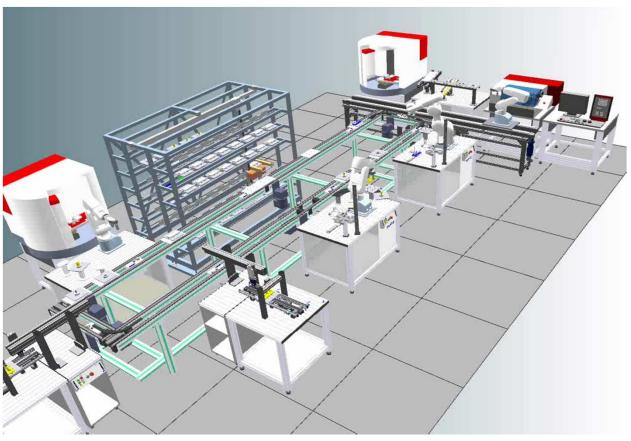






- Alternative software for simulation
- **FESTO** use the software for education

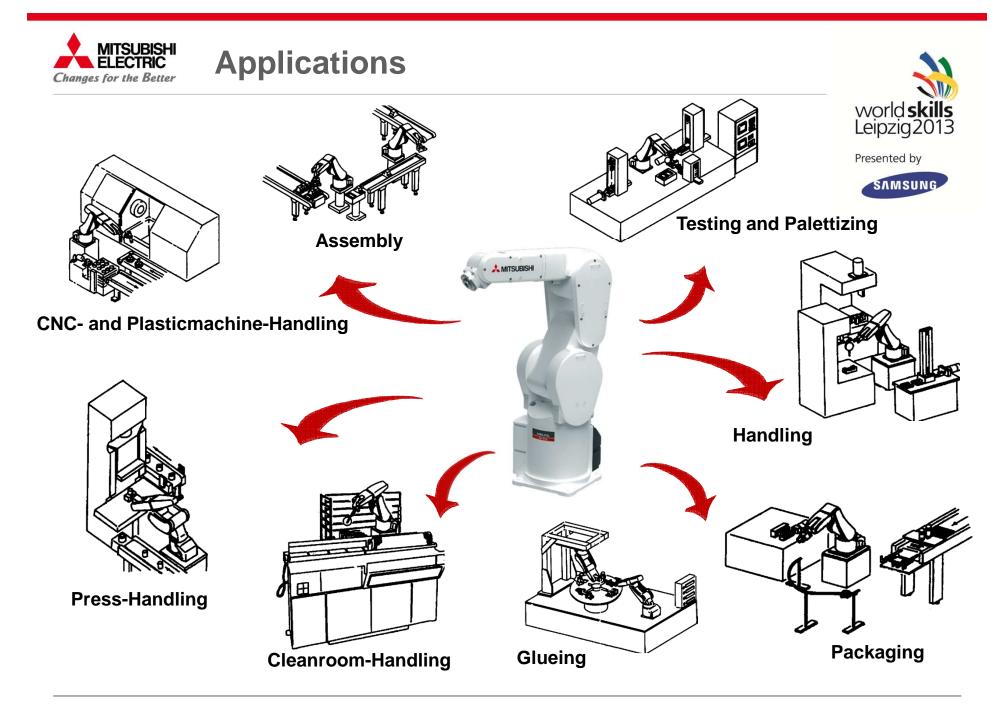








Mitsubishi Electric Robots INDUSTRIAL APPLICATIONS





Packaging

- Camera supported pick and placing
- Conveyor tracking for continuous work flow







Quality control



• Force controlled operation of navigation systems





Industrial applications



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EDUCTIONAL ROBOTS AND PROJECTS

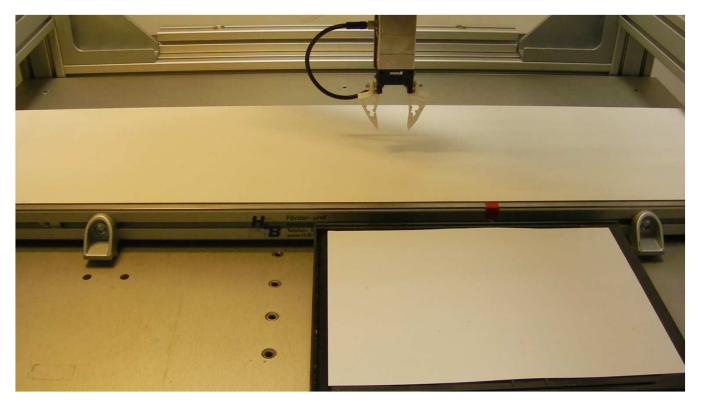
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Energy efficiency

- Pick and place with electrical gripper
- Energy efficiency and increased hygiene

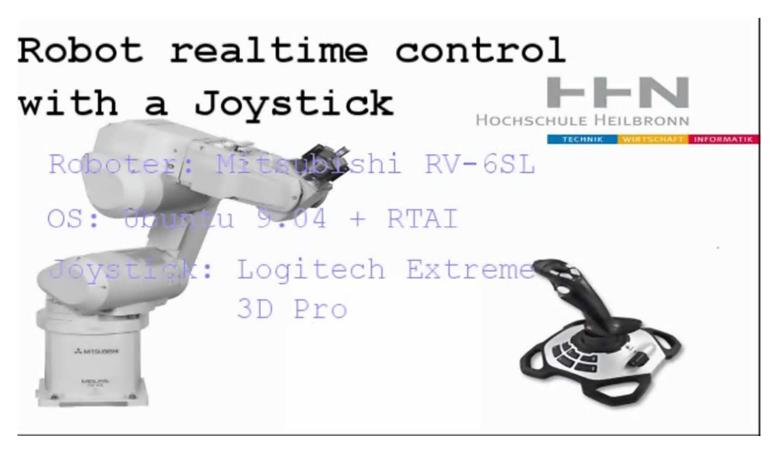






Real-Time control

• Remote control of the robot with a standard joystick



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Real-Time simulation

- Virtual layer on real application
- Ensures robot specifications and feasibility





Bionic transfer

- Learning from nature
- Transferring knowledge to technical fields











INTERACTIVE PART - HALL 3 FESTO HALL - MECHATRONICS